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Different methods, different wilds: Evaluating alternative mappings of wildness using fuzzy MCE and Dempster-Shafer MCE

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Abstract

Different multi-criteria evaluation (MCE) approaches are applied to a fuzzy wildness mapping problem in Scotland. The result of fuzzy weighted linear combination and fuzzy order weighted averaging approaches are compared with the application of a Dempster-Shafer MCE. We discuss the implications of different approaches in light of decision making associated with suitability in a context where (i) suitability (wildness) may not be very well defined, (ii) the decision makers may not fully understand the informatics aspects associated with applying weights, but (iii) require decisions to be accountable and transparent. In such situations we suggest that the outputs of Dempster-Shafer MCE may be more appropriate than a fully fuzzy model of suitability.

1. Introduction

"Wilderness is what men think it is."
Roderick Nash, in Wilderness and the American Mind (1981, p.3)

Wilderness is an essentially human construct based largely on individual perceptions and often romantic notions about nature and landscape. As such, it is notoriously difficult to define in rigorous, scientific and legal terms. In the USA for example, it took Howard Zahniser 8 years to write an acceptable definition of wilderness and get this through congress and onto the statute books as the 1964 Wilderness Act. His poetic and succinct definition identifies wilderness thus: "a wilderness, in contrast with those areas where man and his own works dominate the landscape, is hereby recognized as an area where the earth and its community of life are untrammeled by man, where man himself is a visitor who does not remain." (US Wilderness Act, 1964, p.1). Various studies have taken this and subsequent refinements and attempted to use GIS to map the world's remaining wilderness areas at various spatial scales and resolutions. Global scale maps have been developed by McCloskey and Spalding (1989), and Sanderson et al. (2002). Regional level maps have been developed for Australia (Lesslie, Taylor, & Maslen, 1993), for the USA (Aplet, Thomson, & Wilbert, 2000), and for Europe (Fritz, Carver, & See, 2000). Many of these mapping projects have been based around multi-criteria type approaches as a means of accounting for different priorities between spatial factors relating to wildness (Carver, 1996; Carver, Evans, & Fritz, 2002; Fritz, See, & Carver, 2000) with the resulting maps showing a continuum of environmental modification from the "paved to the primeval" (Nash, 1982, p.3).

Some wildness mapping research has used a multi-criteria evaluation (MCE), using different criteria and combination techniques. The Australian Heritage Commission's National Wilderness Inventory defined wilderness on the basis of four factors: remoteness from settlement, remoteness from access, apparent naturalness, and biophysical naturalness (Lesslie, 1994; Miller, 1995). Minimum levels of remoteness and naturalness were defined and the factors were combined to define a wilderness quality index. Fritz, See, et al. (2000) noted that remoteness and primitiveness cannot be assessed by a single wilderness quality indicator. Instead they proposed that remoteness be described as a proximity function to settled land and settled people and primitiveness could possibly be described as biophysical and apparent disturbance. They weighted the factors according to the results of an internet questionnaire in a fuzzy MCE. Carver et al. (2002) developed variation of the Australian approach using similar factors within a fuzzy...
MCE framework to identify the wilderness continuum in Britain. This identified wilderness using six factors: remoteness from local population, remoteness from national population centres, remoteness from mechanized access, apparent naturalness, biophysical naturalness, and altitude. It used a web application to allow users to explore the impacts of different factor weights on the resulting wilderness maps. The web mapping allowed users to explore their perceptions of wilderness using simple slider bars and a Java application to recalculate and then redraw the continuum map.

A multi-criteria evaluation (MCE) methodology has again been applied in a recent study to map wilderness attributes at high spatial resolutions in the Cairngorm National Park (CNP) in Scotland. The approach focused on GIS-based MCE using weighted linear combination (WLC) and fuzzy methods that were developed during previous work mapping on wild land quality (Carver, 1991, 1996, 2002; Fritz, Carver, et al., 2000) and is reported in Carver et al. (2008). Data were generated for the four principal factors that contribute to wilderness in Scotland as identified Scottish Natural Heritage – the agency responsible for the natural environmental in Scotland. These include perceived naturalness of land cover, absence of modern artefacts, rugged and physically challenging terrain, and remoteness (SNH, 2002). For the purposes of the original project these data were combined using WLC with equal weightings for each factor. The resulting map of wilderness is fuzzy and based on perceptions of wilderness rather than strict ecological definitions. Planning and decision making bodies would like to be able to identify boundaries between ‘wild’ and ‘not wild’ for use in supporting decisions related to planning and developments. For example, those developments that reduce the area of the wild category significantly might be refused planning permission, whereas those that have no or only minimal impact might be allowed to go ahead.

Agencies concerned with planning policy have to determine whether proposed developments fall inside or outside of planning constraints. In many cases, they are given only guidance about how to interpret and apply planning law rather than a set of hard and fast rules. The latter implies a Boolean mapping of different planning zones and the former indicates approaches that incorporate some of the uncertainty relating to the interpretation of planning guidance. The problem faced by planning agencies is how to convert vague guidelines into crisp decisions, typically through the identification of thresholds to determine different categories in the continuum of ‘wildness’.

The problem addressed in this research is complimentary to a broad body of work that has considered fuzzy definitions and fuzzy extent, exemplified by Hwang and Thill (2005, 2009) and latterly Ban and Ahlqvist (2009) who illustrated the uncertainties associated with different definitions and conceptualizations of urban land use. The work described in this paper differs from Ban and Ahlqvist (2009) in two ways. First Ban and Ahlqvist (2009) describe the generation alternative fuzzy set membership values to the set of ‘exurban’ as derived from exurban definitions from the literature. In this work we are not concerned with definitions of ‘wildness’. Second, Ban and Ahlqvist explore the effects of fuzzy set combinatory-operations: fuzzy MIN, fuzzy MAX, fuzzy PRODUCT, a weighted average and an average. In this work we are concerned with the extensions to fuzzy combinatory-operations such as are included in Ordered Weighted Averaging (OWA). These were introduced in an informatics context by Yager (1988) and in a GIS by Jiang and Eastman (2000), Eastman (2006), Malczewski (2006a, 2006b) and Boroushaki and Malczewski (2008). This paper explores different MCE approaches based around OWA for determining ‘wild’ and ‘not wild’ areas. These include Boolean MCE, OWA with different order weights, WLC as a special case of OWA where the order weights are equal and the Dempster-Shafer combination method. Each of these approaches requires some kind of weighting (order or factor) and produces different spatial distributions of wilderness. The scientific motivation for this work was to explore the suitability of the different approaches to support decision making when weightings or expert opinion may not be available.

This paper introduces wilderness mapping and reviews multi-criteria evaluation approaches in Section 2 before describing the methodology in Section 3. The results of applying Boolean and Fuzzy MCE approaches are presented in Section 4, showing different mappings of wilderness and the (non-spatial) distribution of wilderness values generated from the same data by each approach. The results and the different approaches are discussed in Section 5 before some conclusions are drawn.

2. Background

2.1. Wilderness mapping

There has been a great deal of debate in recent years over the definition and applicability of wild land in the UK (e.g. Fenton, 1996; Taylor, 2005). Perhaps the most progress has been in Scotland, where some of the nation’s wildest landscapes can be found in places like the Cairngorm, Rannoch Moor, the Monadhliath and Glen Affric. Here several organisations, taking their lead from the Scottish Office National Planning Policy Guideline 14 (NPPG14) on Natural Heritage (Scottish Office, 1999), have developed their own wild land definitions. These include Scottish Natural Heritage (SNH, 2002), the National Trust for Scotland (National Trust for Scotland, 2002) and the John Muir Trust. NPPG14 defines wild land as:

“Uninhabited and often relatively inaccessible countryside where the influence of human activity on the character and quality of the environment has been minimal” (The Scottish Office, 1999).

The SNH definition, published in 2002 refers to:

“parts of Scotland where the wild character of the landscape, its related recreational value and potential for nature are such that these areas should be safeguarded against inappropriate development or land-use change” (SNH, p.8),

while the NTS further define wild land as:

“relatively remote and inaccessible, not noticeably affected by contemporary human activity, and offers high-quality opportunities to escape from the pressures of everyday living and find physical and spiritual refreshment.” (The National Trust for Scotland, 2002, p.4).

An important aspect of the wild land concept is its subjective and often shifting nature. This is characteristic of the nature of peoples’ differing perceptions of the concept of wilderness and is captured nicely in a further quote by Roderick Nash where he suggests “One man’s wilderness is another’s roadside picnic ground” (Nash, 1982, p.1). This presents an interesting problem that in order to manage a landscape value such as wild land quality, we first need to be able to define it sufficiently rigorously from multiple and often conflicting view points, before we can actually identify and map it.

Both Scottish Natural Heritage and the National Trust for Scotland study consider the main features relating to perceptions of wilderness to be:

(i) Perceived naturalness of land cover – the extent to which land management, or lack of, creates a pattern of vegetation and land cover which appears natural to the casual observer.

(ii) Absence of modern human artefacts – the lack of obvious artificial forms or structures within the visible landscape, including roads, railways, pylons, hard-edged plantation forestry, buildings and other built structures.
(iii) Rugged and challenging nature of the terrain – the physical characteristics of the landscape including effects of steep and rough terrain and harsh weather conditions often found at higher altitudes.

(iv) Remoteness – the remoteness of inaccessibility of the landscape based on time taken to walk from the nearest point of mechanised access.

A full description of each factor is given in Table 1. Currently, there is little quantitative evidence of consumer opinion regarding the ‘wildness’ of Scotland. Therefore, Scottish Natural Heritage and the Cairngorms National Park Authority commissioned a market research study to evaluate public perceptions of wild places amongst a representative cross-section of Scottish residents and a subset amongst those living within the boundaries of the Cairngorms National Park (CNP). The study, conducted by Market Research Partners (2008), identifies the level of support for wild places and whether the views of those who live within CNP match the population of Scotland as a whole. A total of 1304 face to face interviews were conducted, 1064 across Scotland and 300 with residents of the CNP area. Whilst the survey sought to identify the features which make an area wild, it did not ask the respondents directly about the four factors identified by Scottish Natural Heritage as contributing to wildness. Instead the survey report inferred support for these factors by categorising the response to other questions. Carver et al. (2008) revisited the results of the survey and extracted slightly different factor weights based on the responses to unbiased survey questioning. The landscape characteristics and features identified by the Scottish and CNP residents in response to the question “In your opinion, what features or characteristics make an area wild?” (Market Research Partners, 2008, p.9) such as “wildlife”, “Forests/woods/trees”, “Open space”, “Lochs”, “Hills/mountains/glens”, etc. were subjectively allocated to the different factors by Carver et al. (2008). The weights were based on the number of responses identifying each feature. The purpose of this study is not to explore the weights themselves but their behaviour under different combination approaches. The question over which set of factors weights to use in the analysis of fuzzy MCE and the impacts of different order weights was resolved by taking the average of three sets of weights. The weights are shown in Table 2.

### 2.2. Multi-criteria evaluation

Multi-criteria evaluation combines different layers of spatial information or factors in order to generate an aggregated measure of suitability. In a Boolean MCE, the criteria are applied as thresholds to partition layers into unsuitable and suitable areas. The derived layers are then combined in an overlay operation to identify Boolean suitability in one of two ways:

- Intersect (AND) operation, which identifies areas where all conditions are satisfied.
- Union (OR) operation which identifies areas as being suitable if any one of the criteria is met.

By way of illustration the factors contributing to perceptions of wildness in Table 1 are continuous in nature with values from 0 to 255, as a result of a normalisation process as part of the original project brief and described in Carver et al. (2008). These were reclassified using a threshold of 127 to create Boolean masks (i.e. those areas with a value of 0 being labelled suitable and those above 127 as unsuitable). The weights were assigned to each factor in Table 2.

### Table 1
Factors contributing to perceptions of wild land (after SNH, 2002).

<table>
<thead>
<tr>
<th>Factor</th>
<th>Main criteria</th>
<th>Further detail</th>
</tr>
</thead>
<tbody>
<tr>
<td>Perceived naturalness</td>
<td>Vegetation cover primarily composed of functioning, natural habitats. Catchment systems largely unmodified, and other geomorphological processes unaffected by land management</td>
<td>Habitat may often not be in best condition or at optimum ecological status. But there will normally be potential for recovery, and the vegetation cover should be composed of natural components. Some small plantations may be tolerated especially at the edge of an area, if they are the only detracting feature and of limited effect on wildness</td>
</tr>
<tr>
<td>Lack of constructions or other artefacts</td>
<td>No contemporary or recent, built or engineering works within the area</td>
<td>Older features (fences, bridges, stalking tracks, or small buildings) may be present, if not intrusive overall. Archaeological features (normally a light imprint on the land) will contribute to visitors’ appreciation of the continuity of human use of these areas. Some intrusive features (say vehicular tracks which partly penetrate into an area) may be tolerated, where their effects are limited, and where excluding such land would reject an area of high intrinsic quality</td>
</tr>
<tr>
<td>Rugged or otherwise Challenging terrain</td>
<td>Striking topographic features, or land having extensive rough terrain or extensive boglands, difficult to traverse</td>
<td>Different kinds of terrain can offer an inspiring or challenging experience for people but, in the main, it is those landscapes which are of arresting character (by virtue of the scale and form of the terrain) which are most valued for their wildness</td>
</tr>
<tr>
<td>Remoteness and inaccessibility</td>
<td>Distance from settlements or modern communications</td>
<td>Distance is not an absolute guide on its own, but most of the wild land resource will lie in the remaining remote areas, as defined by distance from private and public roads and other artefacts</td>
</tr>
</tbody>
</table>

### Table 2
Sets of factor weights derived from a public perception survey.

<table>
<thead>
<tr>
<th>Factor</th>
<th>Scottish</th>
<th>CNP</th>
<th>Carver et al. (2008)</th>
<th>Average</th>
</tr>
</thead>
<tbody>
<tr>
<td>Naturalness</td>
<td>0.586</td>
<td>0.568</td>
<td>0.516</td>
<td>0.557</td>
</tr>
<tr>
<td>Remoteness</td>
<td>0.250</td>
<td>0.273</td>
<td>0.037</td>
<td>0.187</td>
</tr>
<tr>
<td>Ruggedness</td>
<td>0.039</td>
<td>0.038</td>
<td>0.124</td>
<td>0.067</td>
</tr>
<tr>
<td>Lack of modern artefacts</td>
<td>0.125</td>
<td>0.121</td>
<td>0.323</td>
<td>0.190</td>
</tr>
</tbody>
</table>
of 0 and 1) and then combined using union and intersect operations to identify wild and non-wild areas (Fig. 1).

In many analyses, suitability may not be Boolean in character, but has varying degrees of membership, and each criterion contributes evidence from which fuzzy membership of the set of ‘suitable’ can be determined. The maps in Fig. 1 illustrate the issues associated with applying a Boolean MCE in the context of decision making: thresholds have to be determined for each factor and what Jiang and Eastman (2000) called the “trade-off” between factors has to be managed. The maps in Fig. 1 show different extremes of trade-off. For these reasons and to accommodate some of the uncertainty associated with suitability mapping, fuzzy MCE approaches have been used in many analyses (e.g. Borouchaki & Malczewski, 2008; Jiang & Eastman, 2000; Malczewski, 2006a).

In order to overcome the lack of sensitivity in Boolean MCE approaches, various fuzzy MCE have been developed by different workers. Weighted Linear Combination multi-criteria evaluation (Voogd, 1983), also known the weighted mean, provides a refinement to Boolean combination. It determines suitability based on the weight of criteria contributing to overall suitability:

\[
S_i = \sum_{j=1}^{n} w_j \cdot x_{ij} \quad \text{where} \quad \sum_{j=1}^{n} w_j = 1
\]

where \(S_i\) is the suitability score for site \(i\), \(w_j\) is the weight of criterion \(j\), \(x_{ij}\) is the grading value of site \(i\) under criterion \(j\), and \(n\) is the total number of criteria. In contrast to the Boolean approaches WLC allows trade-off between factors by weighting them according to the importance given to a particular criterion in assessing suitability. One of the difficulties in applying a WLC is how to determine appropriate weights for each of the factors being combined. Analytical Hierarchy Process (AHP) offers a method to overcome this as weights are generated interactively with the respondent (whether they are an expert or not) for input into fuzzy MCE (Bania, 1993; Borouchaki & Malczewski, 2008; Wu, 1998). Numerous AHP interfaces have been written for different GIS software (e.g. Eastman, 2006; Hill, Braaten, Veitch, Lees, & Sharmand, 2005; Marinoni, 2004; Borouchaki & Malczewski, 2008).

Jiang and Eastman (2000) summarised a number of problems with MCE analyses based on Boolean and WLC approaches. First, Boolean analyses produce very different results depending on whether a hard AND or a soft OR operator is used. In contrast, WLC approaches compensate a low score in one criteria with a high score on another, providing trade-off. Second, decision risk (the likelihood that the decision made will be wrong) is not properly dealt with by either approach. In Boolean analyses, decision risk can be estimated by propagating error throughout the decision rule to determine the risk that the decision made at a given location is wrong.

OWA are multi-criteria operators suggested by Yager (1988). Jiang and Eastman (2000) proposed their use in a GIS context as a method to overcome the systematic problems related to risk and trade-off in MCE. OWA provides continuous fuzzy aggregation operations between fuzzy intersection (MIN or AND) and union (MAX or OR), bridging WLC, Boolean and Fuzzy aggregations. It allows a variety of operators between MIN (AND) and MAX (OR), control over the degree of trade-off between factors in MCE and thereby allows the overall level of risk to be controlled. OWA uses two sets of weights: criterion weights, which describe the relative significance of a particular criterion (or factor) for the decision as in WLC, and order weights which are applied to the ranked criteria after the application of the criterion weights. Consider \(j\) attribute maps, a set of criterion weights \((w)\) and a set of order weights \((v)\). The criterion weight \(w_j\) is applied uniformly to the \(j\)th map layer reflecting that layer’s importance. The order weights are assigned to the \(j\)th location’s attribute in decreasing order on a location by location basis (e.g. cell by cell in raster data). Formally, the OWA operator associates a set of order weights \(V = \{v_1, v_2, \ldots, v_n\}\) with the \(i\)th map location such that \(v_j \in [0, 1]\) for \(j = 1, 2, \ldots, n\), and \(\sum_{j=1}^{n} v_j = 1\). It is defined as follows:

\[
\text{OWA}_i = \frac{1}{n} \left( \sum_{j=1}^{n} w_j v_j \right) z_{ij}
\]

where \(z_{i1} \geq z_{i2} \geq \ldots \geq z_{in}\) derives from reordering the criterion values and \(u_j\) is the reordered \(j\)th criterion weight, \(w_j\). Order weights control the degree of trade-off between ANDness and ORness and are defined as follows (equations from Jiang & Eastman, 2000):

\[
\text{ANDness} = (1/(j-1)) \sum (j-i)W_{order}
\]

\[
\text{ORness} = 1 - \text{ANDness}
\]

\[
\text{TradeOff} = 1 - \sqrt{\frac{\sum (W_{order} - 1/j)^2}{j-1}}
\]

where \(j\) is the total number of factors (or attribute maps), \(i\) is the order of factors and \(W_{order}\) is the weight for the factor of the \(i\)th order. OWA provides an alternative to WLC, where the level of trade-off is full and not adjustable. A full description of OWA in a GIS context and the relationship between Risk and Trade-off are provided in Jiang and Eastman (2000).

The OWA approach has been used for many different GIS applications: Rinner and Malczewski (2002) describe the application of OWA to ski resort planning, Malczewski (2006a) its use in watershed management, and Bell, Schuurman, and Hayes (2007) use it to quantify socio-economic gradients in health status. Malczewski (2006b) reviews the use of GIS and MCE. However, whilst OWA provides considerable refinement compared to Boolean overlays and simple WLC, order weights have to be determined. They require a degree of domain expertise in relation to the decision that is to be made using the results of the MCE and an understanding of the informatics aspects of factor weightings.

Fig. 1. The results of Boolean multi-criteria evaluation in the CNP area using union and intersect operators, wild areas are in black and non-wild areas are unshaded.
Thus far the alternatives to Boolean analyses described above have been based around different implementations of fuzzy set theory. Other formalisms for combining data such as Dempster-Shafer Method have also been used to combine spatial data (Comber, Fisher, & Wadsworth, 2004; Kountes, Wilkinson, Burrill, Goffredo, & Migier, 1993; Tangestani & Moore, 2002; Wadsworth & Hall, 2007). Malpica, Alonso, and Sanz (2007) review the use of Dempster-Shafer approaches in GIS. Dempster-Shafer assesses the belief that a hypothesis is ‘provable’ given the evidence (Comber et al., 2004). Dempster-Shafer can be considered as an extension to Bayesian statistics. It assigns a numerical measure of the weight of evidence (mass assignment, m) to sets of hypotheses as well as individual hypotheses. A second piece of evidence is introduced by combining the mass assignments (m and m’) using Dempster’s rule of combination, to create a new mass assignment m”. Dempster’s rule of combination is defined by:

\[ M^*(C) = \sum_{A_i \& B_j \subseteq C} m(A_i) \times m'(B_j) \quad \text{from Parsons, 1994} \]  

(6)

where the combined mass assignment, m”(C), is equal to the sum of the product m(A_i) and m'(B_j) for all i and j such that set A_iB_j equals C. It does not consider the evidence hypothesis by hypothesis as does Bayes’ theorem, rather the evidence is considered in light of the hypotheses. Much recent work describes modifications to Dempster-Shafer theory, but Parsons (1994) provides a clear introduction to the application and mechanics of Dempster-Shafer. Dempster-Shafer explicitly incorporates uncertainty into belief combinations and generates two measures:

- Belief: a measure of the extent to which the evidence supports the hypothesis.
- Plausibility: a measure of the extent to which the evidence does not refute the hypothesis (i.e. Belief with Uncertainty).

The interval between the Plausibility and Belief provides a measure of uncertainty about a specific hypothesis and the Disbelief can be derived as the Belief, Uncertainty and Disbelief sum to unity.

3. Methods

This paper compares the application of different fuzzy approaches for combining spatial data: ordered weighted averaging, weighted linear combination which can be seen as a special case of OWA, and Dempster-Shafer. The study was conducted using data covering the Cairngorm National Park area in north eastern Scotland and the wildness continuum was mapped by combining the four factors contributing to wildness identified by SNH using the different approaches.

3.1. Factor data

The construction of the factor data is described in Carver et al. (2008) and summarised below:

Perceived naturalness was derived from a combination of reclassified datasets including the Land Cover Map 2000 (LCM2000), Land Cover of Scotland 1988 (LCS88) and Highland Birchwoods Woodland Inventory (1999).

Absence of modern human artefacts was constructed from LCM2000 data combined with detailed terrain data and a digital surface model (DSM) and viewshed assessment.

Ruggedness was constructed from a digital terrain model (to derive indices of terrain complexity that take slope, aspect and relative relief) and climate data from local weather stations.

Remoteness was mapped in the CNP based on a GIS implementation of Naismith’s Rule (Naismith, 1892) using detailed terrain and land cover information to estimate the time required to walk from the nearest road or track (Carver & Fritz, 1999)

3.2. Fuzzy MCE using OWA with different order weights

The ordered weighted averaging was implemented inside IDRISI GIS with its embedded OWA module (Eastman, 2006). Each of the four factors contributing to wildness was weighted before combination according to the user defined criterion weights (the average weights from Table 2). First, the OWA process creates an intermediary layer for each factor from the product of the factor layer and the criterion weight for that factor. Next, the weighted values at each location (pixel) are evaluated and ranked from lowest to highest.

The order weights are then applied in the following way: the first order weight is applied to the lowest value, the second order weight to the next lowest, etc. In this case there are four factors requiring four order weights, summing to unity in each set. The different sets of order weights were chosen to represent a spectrum from full ANDness and no trade-off, to some ANDness with trade-off and full ORness. The selection of order weights is returned to in the discussion.

Six sets of order weights were applied. Table 3 shows the numerical relationship between the selected order weights and the ANDness, ORness and TradeOff indices. The order weights have the following characteristics:

![Image](https://via.placeholder.com/150)

**Fig. 2.** An example of the calculating belief and disbelief from the median factor layer value (visibility).

<table>
<thead>
<tr>
<th>OWA operator</th>
<th>OW1</th>
<th>OW2</th>
<th>OW3</th>
<th>OW4</th>
<th>ANDness</th>
<th>ORness</th>
<th>TradeOff</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIN</td>
<td>0.8</td>
<td>0.3</td>
<td>0.1</td>
<td>0</td>
<td>0.5</td>
<td>0.5</td>
<td>0.42</td>
</tr>
<tr>
<td>MAX</td>
<td>0</td>
<td>0</td>
<td>0.5</td>
<td>1</td>
<td>0.05</td>
<td>0.5</td>
<td>0.5</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>OWA operator</th>
<th>OW1</th>
<th>OW2</th>
<th>OW3</th>
<th>OW4</th>
<th>ANDness</th>
<th>ORness</th>
<th>TradeOff</th>
</tr>
</thead>
<tbody>
<tr>
<td>MIN</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>MAX</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

Table 3: The relationship between the selected order weights and the ANDness, ORness and TradeOff indices.
[1, 0, 0, 0] is risk averse with only the lowest value is given any weight. It yielded the minimum operator of fuzzy sets with full ANDness and no trade-off.

[0, 0, 0, 1] is risk taking with only the highest values given any weight. It yielded the maximum operator of fuzzy sets with full ORness and no trade-off.

[0, 0.5, 0.5, 0] is an intermediate operator with intermediate ANDness and ORness, with some trade-off.

[0.5, 0.3, 0.15, 0.05] is an operator with trade-off and a moderate degree of ANDness.

[0.05, 0.15, 0.3, 0.5] is an operator with trade-off and a moderate degree of ORness (risk).

[0.25, 0.25, 0.25, 0.25] is a special case to represent the traditional MCE operator using WLC. Here, the order weights have no impact on the factor weights. This is equivalent to simple

Table 4
Calculation of factor belief and disbelief using median values.

<table>
<thead>
<tr>
<th>Remoteness</th>
<th>Ruggedness</th>
<th>Visibility</th>
<th>Naturalness</th>
</tr>
</thead>
<tbody>
<tr>
<td>Median, x</td>
<td>0.208</td>
<td>0.180</td>
<td>0.373</td>
</tr>
<tr>
<td>If greater than median, belief</td>
<td>1.262x – 0.262</td>
<td>1.220x – 0.220</td>
<td>1.594x – 0.594</td>
</tr>
<tr>
<td>If less than median, disbelief</td>
<td>–4.811x + 1</td>
<td>–5.545x + 1</td>
<td>–2.684x + 1</td>
</tr>
</tbody>
</table>

Fig. 3. Histograms of the distribution of wildness values produced by the different aggregation methods.
weighted Linear Combination which has intermediate ANDness and ORness, and full trade-off.

3.3. Dempster-Shafer MCE

Dempster-Shafer was used to combine the wildness evidence from the four factor layers. No order weights or factor weights were used but each of the four factors were linearly normalised to a maximum–minimum range of 0–1 and then split into two layers (Belief and Disbelief) around their median values (medians were selected as they were thought to be more representative of a central value than mean which is more likely to be influenced by outliers). This was done by calculating the slope from the median to 1 for Belief and from the median to 0 for Disbelief. The slopes for the Visibility layer are shown by way of example in Fig. 2 and the terms for each factor are shown in Table 4.

The factor belief layers were combined using the IDRISI Belief module (Eastman, 2006) to evaluate a hypothesis of ‘wild’ producing three aggregated layers: Belief, Plausibility and Interval. The Belief layer provides a measure of the degree to which the evidence provides concrete support for the hypothesis is the lower bound of the belief in the hypothesis. The Plausibility provides the upper boundary and the Interval records the range between Belief and Plausibility, providing a measure of the uncertainty in the hypothesis.

4. Analyses and results

Data were combined using the different MCE approaches, with order weights applied after the average factor weights from Table 2. Dempster-Shafer used neither factor nor order weights. The results of the Shafer-Method were linearly normalised to a 0–255 range for comparison with the OWA results.

The objective of the analysis was to explore the impact of different weightings and different methods of combining data on the magnitude and spatial distribution of wild land. Histograms were generated for each result layer, normalised to common axes for comparison but also with a variable Y axis to show any detail patterns (Fig. 3).

The histograms in Fig. 3 have very different characteristics as expected.

– The full ANDness in the first set of order weight [1, 0, 0, 0] results in a very conservative distribution of values, grouped towards the lower end of the range. From this distribution, it would be very difficult to label any given pixel as being wild and the membership functions to the set of wildness are low. The distribution has peaks and toughs but is not bimodal. It allocates <0.01% of the pixels a value greater than 127 (from a maximum of 255).

– By contrast the full ORness of the second set of order weights [0, 0, 0, 1] is risk taking resulting in a distribution of wildness values which allocates 58% of the pixels to the highest level of wildness (255) and <0.02% to wildness values less than 128.

– The next set of order weights [0, 0.5, 0.5, 0] with intermediate ANDness and ORness, results in bi-modal distribution of wildness values. The data is cleaved around the wildness membership function of 138/255, potentially providing a point which policy makers may wish to use to allocate land into ‘wild’, ‘not wild’ and perhaps to start investigating ‘intermediate’ or uncertain areas.
- The fourth and fifth sets of order weights ([0.5, 0.3, 0.15, 0.05] and [0.05, 0.15, 0.3, 0.5] respectively) both have a bimodal pattern. These weights have a moderate degree of ANDness and some trade-off with ORness. The differences between their distributions reflected in the degrees of ANDness (more in the latter) and ORness (more in the former) and the associated skew towards one end of the continuum of wildness. Each of these potentially indicates a point of bifurcation between wild and not wild values but with much more uncertainty than with the third set of order weights.

- The sixth set of order weights, [0.25, 0.25, 0.25, 0.25] are equal and equivalent to a simple WLC. The resulting distribution of wildness values is determined only by the average factor weights in Table 2. The wildness values can be seen as the base-
line from which the other sets of order weights operate. It has a bi-modal distribution with a tail towards the lower end of the continuum. A potential divide between wild and not wild values may be identified.

- The final histograms of wildness values are the result of applying the Dempster-Shafer method of combination. The data are pushed out into the tails of the distribution which shows a U-shape, providing a separation of wild and non-wild values.

Fig. 4 shows the application of different sets of order weights and different MCE approaches. The conservative, AND operator \([1, 0, 0, 0]\) produces a hard fuzzy intersection. It identifies areas as being ‘wild’, or more correctly ‘with high memberships to the set of wild’, only if they have high values in the fuzzy criteria. Therefore, the wild areas are a long way from human settlement, in areas of natural vegetation, rugged terrain and where evidence of human activity cannot be seen. Conversely the liberal OR operator \([0, 0, 0, 1]\) identifies a much larger area as being wild taking any single piece of evidence with a high value as an indicator of overall wildness. The operators in between the extremes identify similar core areas with relatively high memberships to wild, but the absolute values and troughs are different. However, they show greater variation in the location of fuzzy wild areas with intermediate memberships to the fuzzy set of wild. In these areas, wildness is more uncertain as they represent areas where the different factors aggregated in the MCE into wildness trade-off against each other: some areas may be natural land cover but with human artefacts visible in the landscape.

The wild areas identified using the Dempster-Shafer method of combination has different characteristics to the other in two ways.

First, the areas with high belief are clearly separable from those with low belief clearly not wild areas. Generally pixels are allocated high or low beliefs but not in between implying that there is little uncertainty associated with the belief. It is instructive to examine the other two outputs of the Dempster-Shafer MCE approach: the interval and the Plausibility layers in Fig. 5. Recall that the Plausibility layer provides a measure of the upper boundary of possible belief (with the Belief layer providing the lower). This means it includes the Belief and the ‘Plausible belief’ – beliefs that could exist. Many areas could have a high belief in wild and the distribution is and extent similar to the full ORness \([0, 0, 0, 1]\) layer. The belief Interval records the range between Belief and Plausibility and provides a measure of the uncertainty. If the layer is examined, the lighter areas indicate where there is greater uncertainty in the belief and the gap between the Belief and the Plausibility is high.

5. Discussion and conclusions

The different mappings produced by the various fuzzy MCE approaches vary from OR approaches that identify large areas with high wildness memberships to AND operators that identify small areas. We note that further sets of order weights could have been selected, for instance possible alternative third sets include \([0.5, 0, 0, 0.5]\), or \([0, 0.5, 0.5, 0]\) or \([0.5, 0.5, 0, 0]\) instead of \([0, 0.5, 0.5, 0]\). Undoubtedly this would produce yet further distributions of wildness values. However, the purpose of this work was to illustrate the variability as a result of applying different order weights in the light of decision making. We have shown that varying the order weights provides a range of operators between full MIN (AND) and full MAX (OR) and, if fully understood, can provide control over the degree of trade-off between factors in MCE against the overall level of risk, or of being incorrect (Jiang & Eastman, 2000). This is because different sets of order weights modify the original factor weighted data and can produce very conservative, very liberal and in between (traded off) mappings of wildness.

In comparing Dempster-Shafer MCE with fuzzy MCE this paper highlights the two approaches: The fuzzy approaches can maintain a full fuzzy model of landscape wildness in their output, whilst Dempster-Shafer partitions evidence from the input data in a way that approaches a Boolean aggregation of fuzzy inputs, as well as providing a separate layer of the uncertainty. The fuzzy approach may be difficult to apply where there are vague definitions of suitability (e.g. of ‘wildness’) held by the decision maker. Dempster-Shafer provides a product which obscures the real doubt by partitioning belief and can give a clear cut definition of wildness and suitability but also provides a model of the uncertainties in the Plausibility layer.

The implications of this are that the selection of method and weights has major implications for the mapped outcome of suitability (in this case of wildness). For a well defined problem, with clear and well understood parameters, there are obvious advantages to an OWA approach: the factor and order weights can be used to constrain the aggregation process in a way that represents the current or best understanding of the problem being examined. But this requires a very robust understand of all the parameters involved in the decision and how they interact to influence the final outcome. In many planning situations, such as at a local government level, this is often not the case making the transparent use of order weights difficult in a fuzzy MCE. The safer option is to use only factor weights, which is often the case in the experience of the authors. The use of and setting of factor weights can be justified in terms of consultants, expert or public opinion. Many decision makers are happy with fuzzy representations of features as
the fuzzy method produces a more faithful picture, reflecting the continuum.

Fuzzy methods, whether Min (AND) or Max (OR) or in between, provide a full fuzzy models of landscape wilderness which are able to better reflect the doubt in the minds of the decision makers about wildland definitions, but only if they are able to understand the GIS technology (common) and understand the informatics aspects involved in order weighting (rare). In many situations where GIS is being applied to map suitability, decision makers may not have a full understanding of how the application of order weights (and therefore trade-off and risk) relate to their problem and how weights interact with the resulting solutions. This informatics aspect is important when assessing trade-off and risk in light of decision making. Analytical Hierarchy Process (AHP) has been suggested as a solution to the problem by providing a tool that integrates fuzzy linguistic operators (Boroushaki & Malczewski, 2008). But AHP still requires the domain knowledge and a well-defined understanding of suitability to understand how to parameterize the input appropriately and then to interpret the rich and fuzzy output in light of those input decisions.

Malczewski (2006b) noted that many real-world decisions are uncertain because they involve some aspects that are unknowable with uncertainty in decision making relating to “uncertainty associated with limited information about the decision situation, and … uncertainty associated with fuzziness (imprecision) concerning the description of the semantic meaning of the events, phenomena or statements themselves” (p.713). For these reasons the justification by policy makers for the selection of any given set of order weights is more problematic given the variation in the results due to trade-off between (already weighted) factors. Although the application or order weights may be scientifically more attractive, allowing for trade-off between full AND and full OR, in terms of decision making, their application may be difficult to justify by non-expert policy makers who need to make transparent decisions such as demarcating wild and non-wild areas. The increasing sophistication of analysis moving from MCE to factor weights to order weights has not increased the ease of decision making. It may be that Dempster-Shafer MCE offers some potential in this area: measures of overall support are clearly separated into high and low measures of fuzzy belief, with additional evidence pushing the belief in a hypothesis towards the tails of the distribution. The result is that small and on their own potentially less significant pieces of information gain in significance when combined with other evidence. This approach could provide decision makers with a readily identifiable separation of belief in wilderness.

In conclusion the work has explored different methods for combining spatial data in a multi-criteria evaluation of wilderness. Fuzzy MCE approaches require the selection of weights the application of which for order weights requires a full understanding of how the factors trade-off against each other in order to control the resulting uncertainty. Combination based on Dempster-Shafer theory of evidenc e has been shown to partition the aggregated datasets into wild and not wild in a way that the fuzzy MCE approaches did not, whilst providing measures of uncertainty in the Plausibility layer. This work has shown that in situations where expert opinion for whatever reason is not available to parameterise the MCE operation (in terms of factor weights, order weights, degrees of acceptable trade-off and thresholds to interpret the resulting aggregation) then Dempster-Shafer can provide an alternative and/or complement to traditional fuzzy MCE approaches for suitability analyses.

In such situations the outputs of Dempster-Shafer MCE may be more appropriate than a fully fuzzy model of suitability. Future work will compare the results of this investigation with an analysis of the distribution of different types of wild land as described in McMorran, Price, and McCvitte (2006) and will evaluate the impact of different data aggregation methods on resulting spatial distributions of different types of wilderness.

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References


